

Prediction of combined effects of fibers and nano-silica on the mechanical properties of self-compacting concrete using artificial neural network

Abstract

In this research, the combined effect of nano-silica particles and three fiber types (steel, polypropylene and glass) on the mechanical properties (compressive, tensile and flexural strength) of reinforced self-compacting concrete (SCC) is evaluated. For this purpose, 70 mixtures in A, B, C, D, E, F and G series representing 0, 1, 2, 3, 4, 5 and 6 percent of nano-silica particles in replacing cement content are cast. Each series involves three different fiber types and content; 0.2, 0.3 and 0.5% volume for steel fiber, 0.1, 0.15 and 0.2% of volume for polypropylene fiber and finally 0.15, 0.2 and 0.3% of volume for glass fiber. The results show that the simultaneous usage of an optimum percentage of fiber and nano-silica particles will improve the mechanical properties of SCC. Moreover, the obtained results from the experimental data are used to train a multi-layer perceptron (MLP) type artificial neural network (ANN). The trained network is then used to predict the effect of various parameters on the desired output namely the flexural tensile strength, tensile strength behavior and compressive strength.

Keywords

Fiber, Self-compacting concrete, Nano-silica, mechanical properties, artificial neural network.

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1 INTRODUCTION

Self-compacting concrete (SCC) was first developed to improve durability and stability of concrete structures in Japan in 1988 (Ozawa *et al.*, 1996). Preliminary studies about workability of SCC were carried out by Ozawa (1989) and Okamura (1993) in Tokyo University (Okamura, 1997; Okamura and Ozawa, 1994). However, concrete is not suitable for most structures such as bridges,

dams and airports because of its low tensile strength resulting a weak formation and high brittleness. To overcome the above barriers, concrete reinforcing steel has been used in various types of structures. Although these bars are centrally placed in concrete and compensate the weakness to high extent, they are expensive and cannot be applied in some cases such as surface of canals and airports overlays. A number of studies have been conducted relating to the behavior of concrete reinforced with randomly distributed fibers under static and dynamic loading conditions (Xu *et al.*, 2012; Amr, 2009; Holschemacher *et al.*, 2010; Al-Rousan, 2013; Majid *et al.*, 2013; Ivorra *et al.*, 2010; Tumadhir, 2012; Xua and Haoa, 2012; Huang and Zuo, 2005; Beigi *et al.*, 2013).

During the last decades string fibers have been used in concrete to solve the aforementioned problem. Rupture of concrete drastically depends on crack formation due to loading or environmental impacts. Variations in temperature and humidity cause microscopic cracks in mortar which centralize on the surface of coarse aggregates. Continuous loading causes the cracks propagate throughout the concrete (Soroushian, 1986). Using different reinforcing fibers in concrete to make Fiber Reinforced Concrete (FRC) is one of the effective methods to prevent crack propagation and compensating the shrinkage induced by low tensile strength of concrete (Seung *et al.*, 2012). The most important properties of fiber concrete are energy absorption, formability and resistance against strikes. These characteristics help FRC to play an important role in concrete technology and to be a cost-effective material in structural issues (Lin, 1992; Su-Taekang *et al.*, 2010; Olivito and Zuccarello, 2010; Seddik and Bencheikh, 2009; Mohammadi *et al.*, 2009; Bencardino *et al.*, 2010). Energy absorption and strengthening of concrete can efficiently reduce the rupture risk in concrete structures, especially under alternative and vibrating loads. It is worth noting that rupture strain for a brittle matrix (like Portland cement), is much less (less than 1.5) than that of a strong fiber (like steel, glass and polypropylene). Therefore, when FRC is subjected to impact loading, cracks occurrence in matrix is much faster than the rupture occurrence in fibers. Contact area which is also called border layer, is a border area between mortar and the surface of aggregates or fibers or reinforcing bars which plays an important role in permeability, durability and strength of concrete.

Micro-structural characteristics of this area are quite different from mortar containing more pores and micro-cracks. Thickness of contact area depends on the type of fibers, cement, pozzolanic material, water/cement ratio and also concrete age. In this experimental study nano-silica was used as an artificial pozzolan to reinforce the contact area. The addition of nano-SiO₂ into concrete mixtures has been studied by a number of researchers (Qing *et al.*, 2007; Collepardi *et al.*, 2007; Naji *et al.*, 2011; Nazari and Shadi Riahi, 2011; Shekari and Razzaghi, 2011; Tavakoli *et al.*, 2014). Therefore, nano-silica can increase compressive strength of mortar and bonding strength of mortar-aggregates and mortar-fibers interfaces; resulting in an improvement in the structural properties of contact area.

Artificial neural networks (ANN) were previously used to predicting the concrete properties (Flood *et al.*, 2001; Pannir selvam *et al.*, 2008; Perera *et al.*, 2010; Yang *et al.*, 2008; Guang and Zong, 2000; Goh ATC, 1995; Sanad and Saka, 2001; Jamal *et al.*, 2007; Arslan, 2009; Arslan *et al.*, 2007). From a literature study it could be found that there is no investigation on the combined effects of fibers and nano-silica on the mechanical Properties of SCC using ANN.

In this study, the obtained results from the experimental data are used to train the MLP type of ANN. To train the present MLP-ANN; the percentage of nano particles and fiber as the inputs and flexural tensile strength, tensile strength behavior and compressive strength as the outputs of the network are used. The trained network is then used to predict the effect of various parameters on the desired output.

2 MATERIAL PROPERTIES AND EXPERIMENTAL SETUP

2.1 Material

To carry out the experimental Investigation, an amorphous nano-silica (nano-SiO₂, Meyco MP320, BASF) with a solid content of more than 99% is used. Physical properties of these materials are shown in table (1). The nano-silica content for different cases was 2, 4, and 6 wt%. In this study, a super plasticizer (SP) of carboxylic ether (Glenium-110P, BASF) with specific gravity 1.1 gr/cm³ (at 20°C) and three types of reinforcing fibers namely polypropylene (PP fibers, peypolsazan), stainless steel (DUOLOC 36/0.8, BASF) and glass (Chopped Strand, bloorintar) (See Fig.(1) and Table (2)) were used.

Diameter (nm)	Surface– volume ratio (m ² /g)	Density (g/cm ³)	Purity (%)
15 ± 5	160 ± 20	<0.15	>99.9

Table 1: Properties of nano-Silica.

Type	Length (mm)	diameter (mm)	Tensile strength (MPa)	Aspect ratio l/d	Elastic modulus (GPa)	Density (g/cm ³)
Steel	36	0.7	2100	50	160	7.8
polypropylene	12	0.1	450	120	5	0.9
Glass	12	0.1	1400	600	87	2.65

Table 2: Properties of the reinforcing fibers.



Figure 1: Different types of fibers used in this investigation: (a) steel, (b) polypropylene, (c) Glass.

The size of gravel was less than 12.5 mm³ and in accordance with ASTM standard of grading curve. The sand was selected from sieve No. 4.75mm equivalent to 76-percent sand. Cement was of Portland type II and specific gravity of limestone powder was 2.6 gr/cm³.

In the present work seventy mixtures in A, B, C, D, E, F and G categories representing 0, 1, 2, 3, 4, 5 and 6 percent of nano-silica particles replacing cement content were cast. Each series involves three different fiber type and content; 0.2, 0.3 and 0.5% volume for steel fiber, 0.1, 0.15 and 0.2% of volume for polypropylene fiber and finally 0.15, 0.2 and 0.3% of volume for glass fiber. In all 70 samples, all variables were the same except for the fiber type and contents of fibers and nano-silica. The sample with Water/cement (nano-silica + cement) ratio of 0.39 and the sample with no fibers and nano-silica were considered as the control sample (V_f in Table (3) is the volume percent of fiber, i.e. fiber to concrete volume ratio).

2.2 Curing and maintaining the samples

Once the mixing process was completed, the samples were placed into molds and kept under laboratory condition for 24 hours. They were then removed from the molds and kept in 22-25°C water until the suitable age (28 days) for each experiment. Each mixing design included nine 100×100×100mm cubic molds, six 300×150mm cylindrical molds and three 500×100×100mm beam molds. There were a total of 1260 samples for 70 mix design protocols.

2.3 Experimental setup

Compressive strength test was conducted according to the standard B.S1881:Part116. In these assessments, curing condition and experimental and the sample production parameters were the same. Tensile strength test was used, according to the standard ASTM C496 to determine concrete splitting tensile strength. Flexural strength test was performed on a hydraulic Universal Testing Machine (UTM) equipped with displacement speed Control mechanism (displacement rate of 0.5 mm/min) according to the standard ASTM C1018-94b. The samples were 100×100×500 mm prismatic mixes. The distance between the two supports was 40 cm.

3 ARTIFICIAL NEURAL NETWORKS (ANN)

3.1 Modeling using MLP-type neural networks

Unknown function approximation has attracted a great deal of research from different areas such as statistic, data mining, and engineering sciences. Among various types of function approximation tools, artificial neural networks provide a framework which can learn or approximate any function from given data samples through a training process. One of the most important features of a neural network is its flexibility and ability to learn complicated relationships based on the data. Various neural network architectures exist, of which the most popular is the feedforward multi-layer perceptron (MLP). An MLP type of neural network consists of one input layer; one or more hidden layer(s) and one output layer with a large number of inter connected neurons. Fig. (2) shows the basic structure of a typical MLP network.

An example of a MLP type of neural network with one input node, a single hidden layer with two neuron and one output neuron is shown in Fig.(3). An additional input called bias with constant value of 1 is added to the previous input node which works as a shift operator. Each input

node is related to each neuron in hidden layer by a connecting weight. The sum of the products of the weights and the inputs is calculated by each neuron in hidden layer and then treated by an activation function. The obtained result is then multiplied by the associated weight C_3 and again the previous procedure will be repeated in the output neuron. In the present study hyperbolic tangent and linear functions are used as the activation functions in the hidden and output layers respectively.

The final output of the current network is calculated as

$$Network\ output\ (NO) = F_1(x_1) + F_2(x_1) = F(x_1) \tag{1}$$

where,

$$F_1(x_1) = C_3 \tanh(C_1 x_1 + C_2) \tag{2}$$

Once the number of layers and the number of neurons in each layer, have been selected, the network's weights must be adjusted to minimize the prediction error made by the network. This is the general role of the training algorithms. In this investigation Back-propagation (BP) method is applied to train the ANN which is the most widely used learning process in neural networks today.

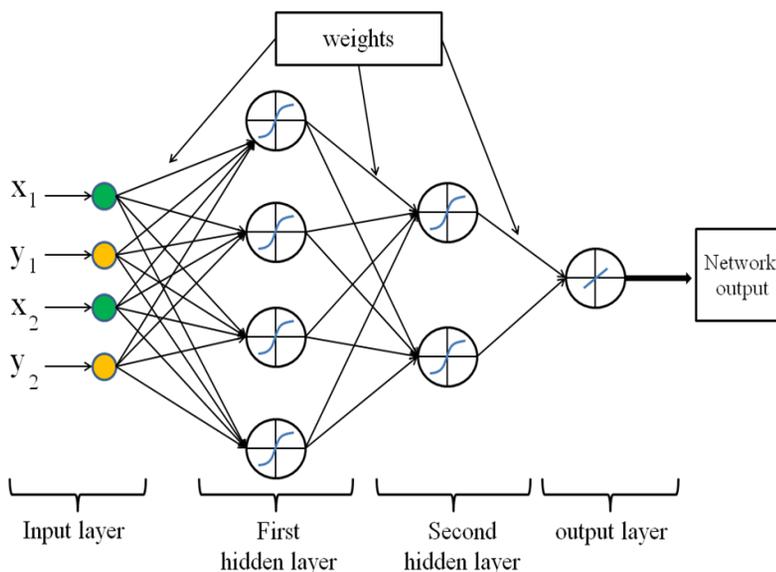


Figure 2: The structure of an MLP-type network.

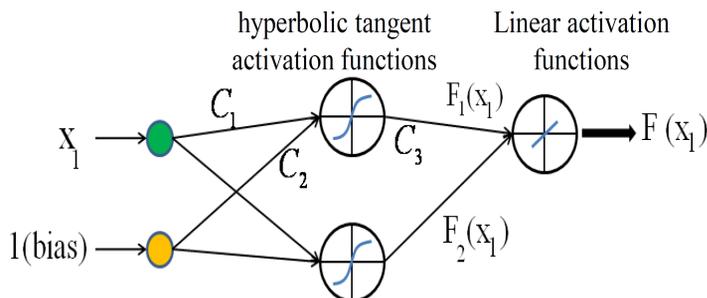


Figure 3: Architecture of a network with one hidden layer containing two neurons and one neuron in the output layer.

3.2 Back-Propagation algorithm

Back-propagation was firstly proposed by Werbos (Werbos, 1974) which is based on searching an error surface (error as a function of ANN weights) using the gradient descent algorithm for points with minimum error.

Consider a network with one hidden layer and one output neuron as shown in Fig (4).

When a set of input data (input vector) are propagated through the network, for the current set of weights there is an output *Est*. The training of perceptron is a supervised learning algorithm where weights are adjusted to minimize the absolute error between the estimated output *Est* of network and the desired output *Des* whenever the estimated output does not match the desired output. If the network error (*NE*) is defined as:

$$Network\ Error = Est - Des = NE \tag{3}$$

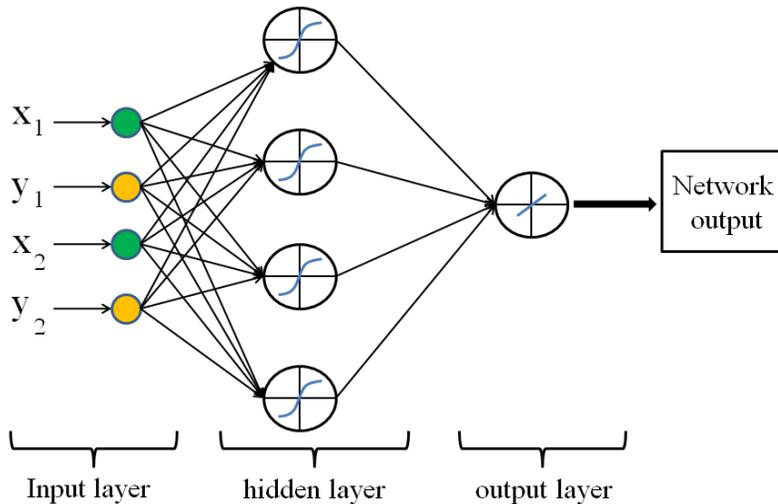


Figure 4: A feed-forward multi-layer perceptron type of neural network with one hidden layer.

The training algorithm should adjust the weights to minimize NE^2 . For this purpose an artificial neuron with its basic elements is considered as shown in Fig .(5). The neuron consists of three basic components; weights, a summing junction and an activation function.

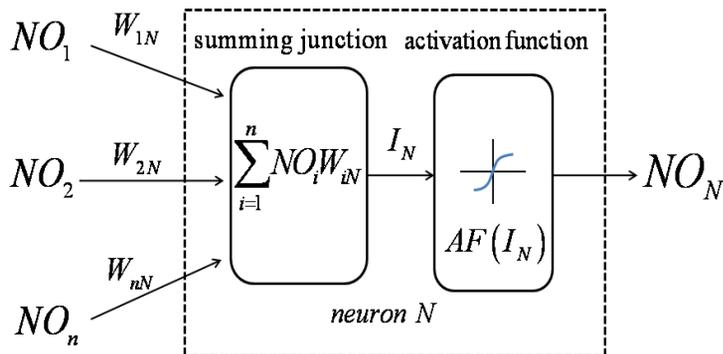


Figure 5: Basic elements of an artificial neuron

The outputs of n neurons NO_1, \dots, NO_n lead in neuron N as the inputs. If neuron N is in the hidden layer then this is the input vector of the network. These outputs are multiplied by the associated weights W_{1N}, \dots, W_{nN} . The summing junction adds together all these products to provide the input I_N for activation function of neuron N . Then I_N passes through the activation function $AF(\)$ and gives the final output of neuron N , which is NO_N .

To commence the calculations, consider neuron M and weight W_{MN} which connects the two neurons. The equation for weight update is as follows

$$W_{MN(\text{adjusted})} = W_{MN(\text{old})} - LR \cdot \frac{\partial(NE^2)}{\partial W_{MN}} \tag{4}$$

where LR is the learning rate parameter and $\partial(NE^2)/\partial W_{MN}$ is error gradient with reference to the weight W_{MN} . The chain rule gives

$$\frac{\partial(NE^2)}{\partial W_{MN}} = \frac{\partial(NE^2)}{\partial I_N} \frac{\partial I_N}{\partial W_{MN}} \tag{5}$$

since the rest of the inputs to neuron N are independent of the weight W_{MN} we have

$$\frac{\partial I_N}{\partial W_{MN}} = \frac{\partial \sum_{i=1}^n NO_i W_{iN}}{\partial W_{MN}} = \frac{\partial NO_M W_{MN}}{\partial W_{MN}} + \frac{\partial \sum_{i=2}^n NO_i W_{iN}}{\partial W_{MN}} = NO_M \tag{6}$$

Eqs. (4), (5) and (6) give

$$W_{MN(\text{adjusted})} = W_{MN(\text{old})} - LR \cdot \frac{\partial(NE^2)}{\partial I_N} NO_M \tag{7}$$

For the case N is an output neuron we have:

$$\begin{aligned} \partial(NE^2) &= \partial(Est - Des)^2 \longrightarrow \\ \frac{\partial(NE^2)}{\partial I_N} &= 2(Est - Des) \frac{\partial Est}{\partial I_N} = 2(NE) \frac{\partial AF(I_N)}{\partial I_N} = 2(NE) \times AF'(I_N) \end{aligned} \tag{8}$$

Substituting Eq. (8) into Eq. (7) gives

$$W_{MN(\text{adjusted})} = W_{MN(\text{old})} - LR \cdot NO_M \cdot 2(NE) \times AF'(I_N) \tag{9}$$

For hyperbolic tangent and linear activation functions $AF'(I_N)$ and the final form of weight update rule can be written as follows

$$\text{For hyperbolic tangent: } \begin{cases} AF'(I_N) = 1 - [AF(I_N)]^2 \longrightarrow \\ W_{MN(\text{adjusted})} = W_{MN(\text{old})} - LR \cdot NO_M \cdot 2(NE) \times (1 - [AF(I_N)]^2) \end{cases} \tag{10}$$

$$\text{for linear functions: } \begin{cases} AF'(I_N) = 1 \\ W_{MN(\text{adjusted})} = W_{MN(\text{old})} - LR \cdot NO_M \cdot 2(NE) \end{cases} \tag{11}$$

When N is a hidden layer neuron

$$\frac{\partial(NE)^2}{\partial I_N} = \frac{\partial(NE^2)}{\partial I_{on}} \frac{\partial I_{on}}{\partial NO_N} \frac{\partial NO_N}{\partial I_N} \tag{12}$$

where the subscript *on* represents the output neuron. In Eq. (12) we have

$$\begin{aligned} \frac{\partial NO_N}{\partial I_N} &= \frac{\partial AF(I_N)}{\partial I_N} = AF'(I_N), \\ \frac{\partial I_{on}}{\partial NO_N} &= \frac{\partial \sum_i NO_i W_{i on}}{\partial NO_N} = \frac{\partial NO_N W_{N on}}{\partial NO_N} + \frac{\partial \sum_{i \neq N} NO_i W_{i on}}{\partial NO_N} = W_{N on} \end{aligned} \tag{13}$$

substituting Eq. (13) into Eq. (12) gives

$$\frac{\partial(NE^2)}{\partial I_N} = \frac{\partial(NE^2)}{\partial I_{on}} W_{N on} \times AF'(I_N) \tag{14}$$

In Eq. (14), $\partial(NE^2)/\partial I_N$ is now written as a function of $\partial(NE^2)/\partial I_{on}$ which was calculated in Equation (8).

Hence the weight update rule for a hidden layer neuron takes the following form

$$W_{MN(\text{adjusted})} = W_{MN(\text{old})} - LR \cdot NO_M \frac{\partial(NE^2)}{\partial I_{on}} W_{N on} \times AF'(I_N) \tag{15}$$

3.3 Performance of neural network

The most common parameters for evaluation of a neural network’s performance are minimum total squared errors (or RMS error) and minimum total absolute error [DTI, 1994] (or MAE error). MAE and RMS errors are defined as

$$\text{RMS error: } \sqrt{\frac{\sum_{i=1}^n (Des_i - Est_i)^2}{n}} \tag{16}$$

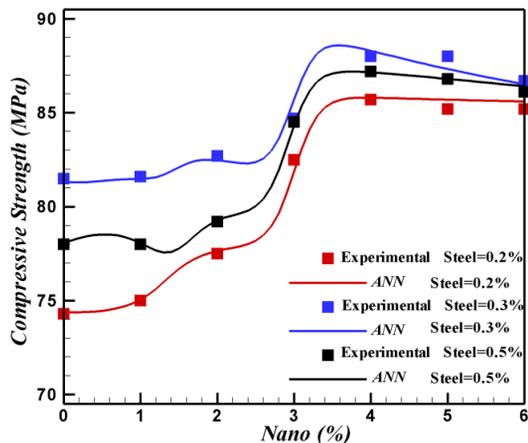
$$\text{MAE error: } \frac{\sum_{i=1}^n |Des_i - Est_i|}{n} \tag{17}$$

where n is the number of training data. The number of hidden layers and the neurons in each of them should be determined in a way to minimum the above errors.

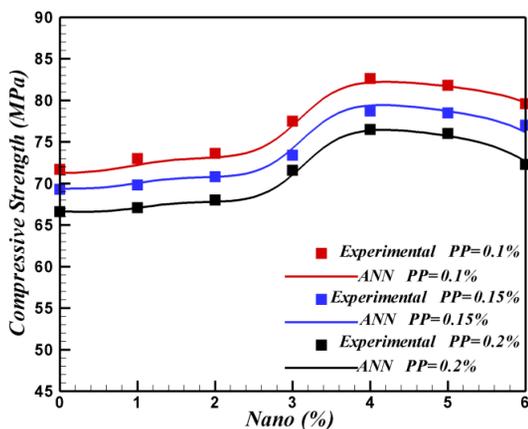
4 RESULTS AND DISCUSSION

4.1 Compressive strength

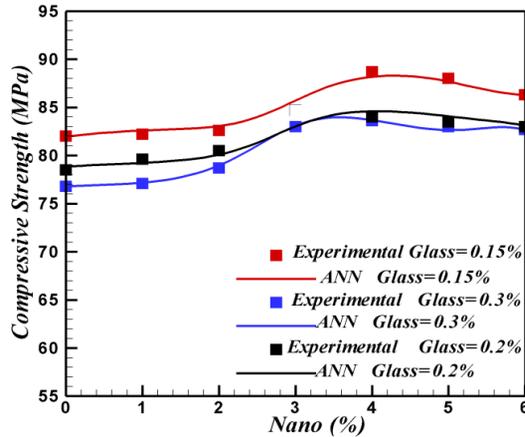
As seen in fig.(6a), the compressive strength initially increases as the content of fibers growth up to 0.3 v% while further increment in the value of fiber content up to 0.5 V%, decreases the compressive strength. As shown in fig. (6b)the compressive strength decrease as polypropylene fiber percent increases. In addition, an increasing trend in compressive strength is observed in fig. (6c). This observation is consistent with those of Guang NH and Zong WJ [2000].



(a) Steel fibers.



(b) PP fibers.

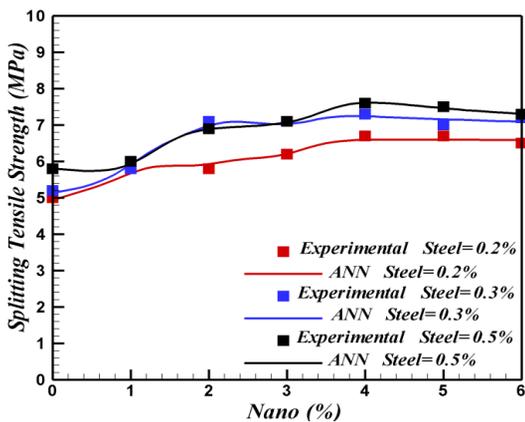


(c) Glass fibers.

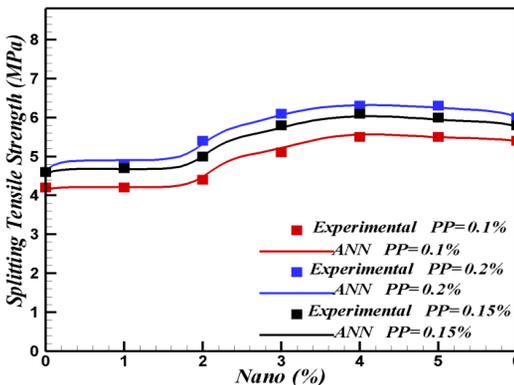
Figure 6: Compressive strength of the samples containing: a) Steel fibers, b) PP fibers, c) Glass fibers.

4.2 Splitting tensile strength

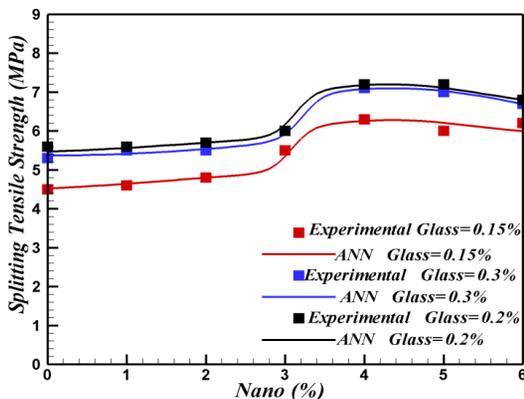
Fig. (7) shows the tensile strength behavior of nano-silica-reinforced concrete with different contents of reinforcing fibers including steel, polypropylene and glass fibers. Stress-strain curves for all fibers show a relatively similar trend: An initial linear increasing trend which reaches to a maximum point, followed by a rather plateau section. This observation is consistent with those of Su-Tae Kang *et al.* (2010). An increase in the content of steel, polypropylene and glass fibers was accompanied by a 45%, 15%, and 33% increase in tensile strength of the sample, respectively. However, addition of nanosilica to the sample, dramatically improved these increases so that tensile strength reached to 90%, 57% and 77%, respectively. This improvement can be attributed to the larger contact area between fibers and mortar resulting in more friction and higher performance of the concrete.



(a) Steel fibers.



(b) PP fibers.



(c) Glass fibers.

Figure 7: Tensile strength of the samples containing: a) Steel fibers; b) PP fibers; c) Glass fibers.

4.3 Flexural strength

Fig.(8) shows a direct relationship between the flexural tensile strength and content of reinforcing fibers (steel, polypropylene and glass). Maximum increase in flexural strength equals 7.08, 6.6 and 8.1 MPa when there is an increase of 0.5 V% in steel, 0.2 V% in polypropylene and 0.2 V% in glass fibers, respectively. The main important role of adding reinforcing fibers to concrete is making links between cracks produced by different causes. If the fibers in volume unit have enough density, strength and are well adhered to cement matrix, they can limit the spread of cracks and give the fiber-reinforced concrete efficient tolerance against greater stresses after the appearance of cracks. This also improves the formability of concrete after the appearance of cracks. For better understand the influence of nano-silica and fiber in mixture, force- deflection behavior of concrete mixtures without fiber are shown in Fig.(9). It can be observed that reinforced matrices exhibit high strength compared to un-reinforced matrix. As seen in the figure, with increasing in Percentage of fibers,

peak load has risen and the softening branch, especially in beams containing steel fiber is developed. This could be due to reinforcement properties and bridging fibers, and consequently an increase in the tensile strength and flexural strength.

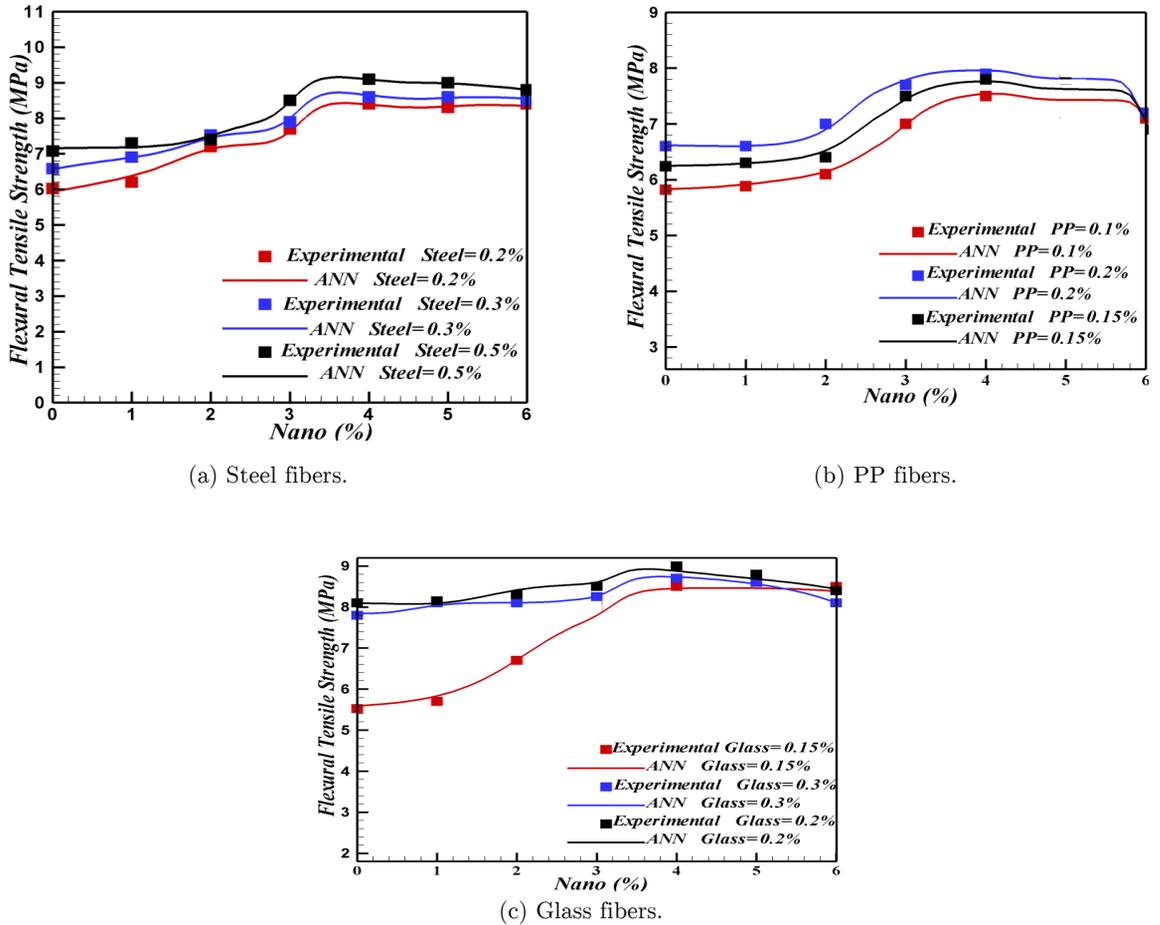


Figure 8: Flexural strength of the samples containing: a) Steel fibers; b) PP fibers; c) Glass fibers.

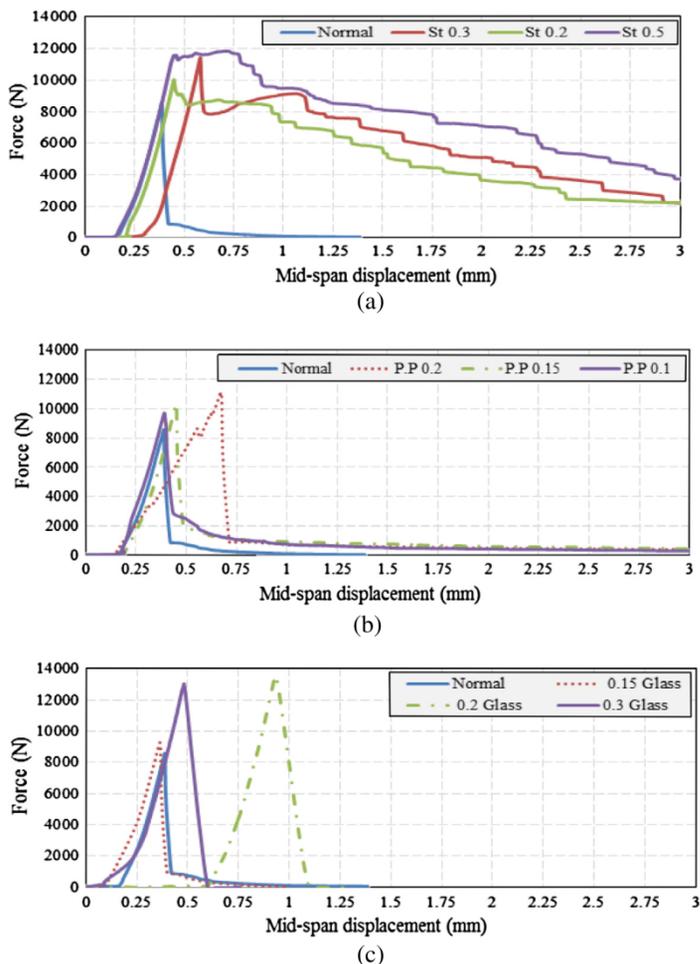


Figure 9: Force–displacement curves for samples with different contents of fibers: (a)Steel, (b)polypropylene and (c)glass.

4.4 Modeling of output using MLP-type neural network

The input–output data pairs used in the present work consist of two input variables, namely the nano and fiber percent and three outputs are flexural tensile strength, tensile strength behavior and compressive strength obtained from experimental tests. Before training procedure the data set was normalized to their mean value and standard deviation 1. A training set of 25 out of 28 input–output data pairs is used to train the MLP-type neural network with only one hidden layer based on BP algorithm. The remaining 3 data pairs are used to test the network performance. Since there are two input variables the network has two neurons in the input layer and one neuron in the output layer. Hence there is no specific method to determine the number of neurons in the hidden layer, trial and error was used. Fig.(10) depicts the effect of different neural network architecture (different number of neurons in the hidden layer) on the RMS error of the network obtained from the normalized data. As can be seen a network with 15 neurons in the hidden layer has an acceptable performance.

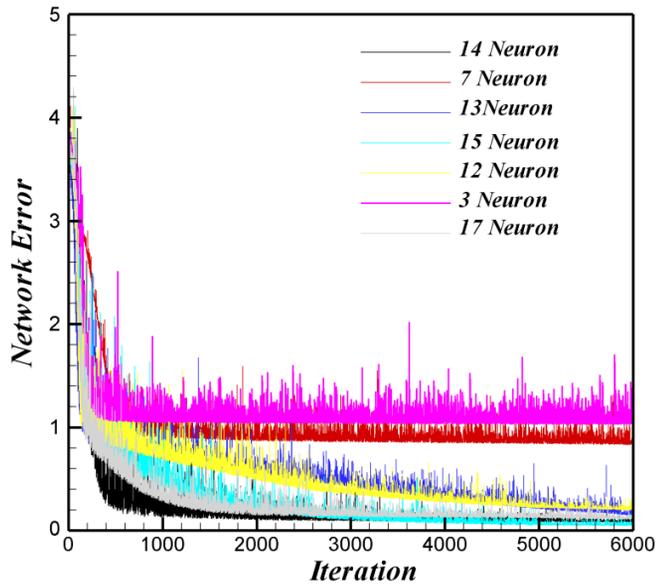


Figure 10: effects of the number of hidden neurons on the network performance for PP fiber and nano-silica particles.

The excellent behavior of the MLP-type neural network for both training and testing data for the present case is also shown in Fig. (11). The figure reveals that the trained network is able to model and predict the outputs successfully.

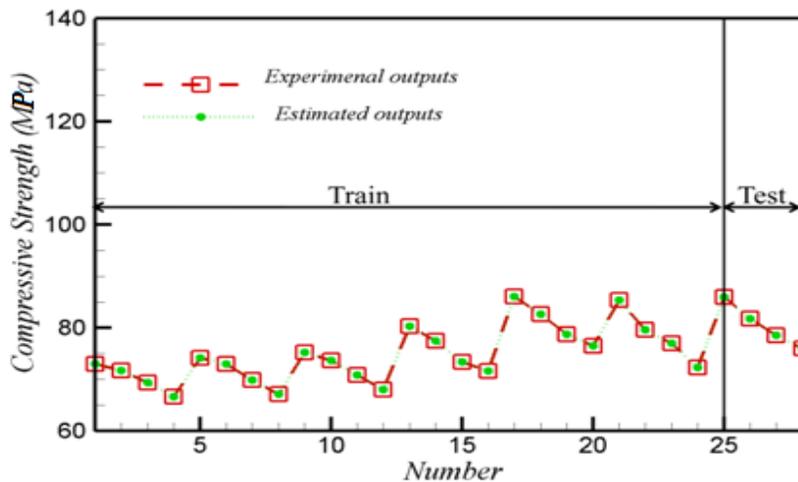


Figure 11: Performance evaluation of the neural network in prediction of G_F for PP and nano-silica particles.

Nano-Silica (%)	V_F (%)	Compressive strength (MPa)	Splitting tensile strength (MPa)	Flexural strength (MPa)	Nano-Silica (%)	V_F (%)	Compressive strength (MPa)	Splitting tensile strength (MPa)	Flexural strength (MPa)		
0	-	73	4	5.16	4	-	86.1	5.4	7.2		
	Steel	0.2	74.3	5		6.02	0.2	85.7	6.7	8.4	
		0.3	81.5	5.2		6.58	0.3	88	7.3	8.6	
		0.5	78	5.8		7.08	0.5	87.2	7.6	9.1	
	PP	0.1	71.7	4.2		5.82	0.1	82.6	5.5	7.5	
		0.15	69.3	4.6		6.24	0.15	78.7	6.1	7.8	
		0.2	66.6	4.6		6.6	0.2	76.5	6.3	7.9	
	Glass	0.15	82	4.5		5.52	0.15	88.7	6.3	8.5	
		0.2	78.5	5.6		8.1	0.2	84	7.2	9	
		0.3	76.8	5.3		7.8	0.3	83.6	7.1	8.7	
	1	-	74.1	4.1		5.3	5	-	8.6	5.3	7.2
		Steel	0.2	75		5.8		6.2	0.2	85.2	6.7
0.3			81.6	5.8	6.9	0.3		88	7	8.6	
0.5			78	6	7.3	0.5		86.8	7.5	9	
PP		0.1	73	4.2	5.88	0.1		81.8	5.5	7.2	
		0.15	69.8	4.7	6.3	0.15		78.5	6	7.8	
		0.2	67.1	4.8	6.6	0.2		76	6.3	7.8	
Glass		0.15	82.2	4.6	5.7	0.15		88	6.2	8.2	
		0.2	79.6	5.6	8.15	0.2		83.2	7.2	8.8	
		0.3	77.1	5.5	8.1	0.3		83	7	8.6	
2		-	75.2	4.3	5.52	6		-	85.4	5.4	7.17
		Steel	0.2	77.5	5.8			7.2	0.2	85.2	6.5
	0.3		82.7	7.1	7.53		0.3	86.7	7.2	8.5	
	0.5		79.2	6.9	7.4		0.5	86.1	7.3	8.8	
	PP	0.1	73.6	4.4	6.1		0.1	79.6	5.4	7.1	
		0.15	70.8	5	6.4		0.15	77	5.8	6.9	
		0.2	68	5.4	7		0.2	72.3	6	7.2	
	Glass	0.15	82.6	4.8	6.7		0.15	86.5	6	8.5	
		0.2	80.5	5.7	8.3		0.2	83	6.8	8.4	
		0.3	78.7	5.5	8.1		0.3	82.7	6.7	8.1	
	3	-	80.3	5	6			-			
		Steel	0.2	82.5	6.2			7.7			
0.3			84.7	7.1	7.9						
0.5			84.5	7.1	8.5						
PP		0.1	77.5	5.1	7						
		0.15	73.4	5.8	7.5						
		0.2	71.6	6.1	7.7						
Glass		0.15	84.7	5.5	8						
		0.2	83.5	6	8.5						
		0.3	83	6	8.25						

Table 3: Physical properties of the hardened concrete (28days).

5 CONCLUSIONS

In this paper an MLP-ANN was used to estimate the combined effects of fibers and nano-silica on the mechanical Properties (flexural tensile strength, tensile strength behavior and compressive strength) of SCC. From this investigation, some conclusions can be summarized as follows:

Fibers are very strong under tension or bending-induced tension. Having this property in mind and evaluating the results of the compressive assessments, it can be concluded that. An increase in the number of fibers per volume unit of concrete initially increases the strength and consequently formability of the samples up to the splitting point. Any further increase of the fibers can result in fiber balling. In this condition, fibers are not only helpful, but also make holes and pores in the mixture.

Mechanical properties such as compressive, flexural and tensile strength are initially increased by the increase of nano-silica content up to 4wt% and then decreased. The increase in strength is because of nano-silica pozzolanic reactions while its decrease is because of high specific surface of nano-particles. When the content of nano-particles increases beyond a certain value (optimal percentage), they will stick to each other through a physical reaction leading unstable balls. An increase of 4wt% of nano-silica is considered as optimal value in this experimental study.

Concretes with different fibers showed different mechanical properties. In case of metal fiber reinforced concrete, increasing the fiber up to 3 V% initially increases the compressive strength up to a maximum value and then decreases the compressive strength, while flexural and tensile splitting strengths follow a relatively linear increment. In polypropylene fibers-reinforced concrete, by increasing the percentage of fibers, compressive strength decreases while flexural and tensile strengths increases. In the glass fiber-reinforced concrete, compressive strength was totally higher than the reference specimen; however, increase of fiber content, decreases compressive strength and increases the flexural and tensile strengths.

Findings of the flexural assessments among the mixtures showed that increasing the content of fibers, especially metal fiber, increases the tensile and flexural strengths and therefore, the consequent formability is significantly increased. Moreover, increase of the nano-silica content up to 4 wt%, enhances the tensile and flexural strengths more significantly which is because of the filling and pozzolanic effects of nano-silica in contact area between fibers and cement matrix.

In order to predict the compressive strength, tensile strength behavior and flexural tensile strength, models were constructed by MLP-ANN method.

The comparison revealed that the obtained results from ANN are in a good agreement with the experimental ones.

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